Designing Random Allocation Mechanisms: Theory and Applications

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- House allocation. (Chen and Sonmez, 2002)
- Organ transplantation. (Roth, Sonmez and Unver, 2004)
- Office assignment. (Baccara et al, 2009)
- Course allocation. (Budish and Cantillon, 2009)
- Deterministic allocations are unfair, when
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• A typical method: (i) Select a set of ex post desirable allocations, and (ii) "randomize" among them: (e.g., Random serial dictatorship, Gale-Shapley DA, Top trading cycles with ties)

 \Rightarrow entails ex ante inefficiencies.

- Alternative method: Choose directly "lotteries of goods" for the agents, called random assignment.
 - The Walrasian "pseudo-market" mechanism (Hylland and Zeckhauser 1979),
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- An issue: What random assignments are implementable? I.e., given a random assignment, is there always a lottery over sure outcomes that realizes it?

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• Implementing random assignments is nontrivial since assignments need to be "correlated." Consider assigning 3 goods *a*, *b*, *c* to 3 agents 1, 2, 3, one for each. Can express an arbitrary random assignment in a matrix form:

$$\mathbf{P} = \begin{pmatrix} 0.5 & 0.5 & 0 \\ 0 & 0.5 & 0.5 \\ 0.5 & 0 & 0.5 \end{pmatrix} = \begin{pmatrix} & & \\ & & \\ & & \\ \end{pmatrix}$$

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The RA method (including HZ and BM) has been applied primarily to an one-to-one assignment problem. To gain practical applicability,

- the model need to be generalized to allow for many-to-one, many-to-many matchings, and unassignment.
- the method must be extended to accommodate a variety of constraints:
 - Group-specific quota ("Controlled choice"): School systems seek balance in student body based on race, ethnicity, gender, test scores (NYC, EdOpt), residence (Seoul).
 ⇒ Sub-column constraint.
 - Within agent constraint: Scheduling and curriculum constraints in course allocation ⇒ Sub-row constraint.
 - Endogenous capacities: Schools may run multiple programs the relative sizes of which are adjustable.
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What we do

- We generalize Birkhoff-von Neumann theorem for implementation of random assignments in general environment:
 - Identify a sufficient condition under which a random assignment can be implemented, called "bihierarchy"
 - Show that the sufficient condition is also necessary in bilateral matching
 - Develop a polynomial time algorithm for implementation
- We extend the random assignment method to market-design applications
 - Generalize Bogomolnaia and Moulin's probabilistic serial mechanism for applications such as school choice
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Find a way to improve ex post fairness in multi-unit assignment and two-sided matching

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- Find a way to improve ex post fairness in multi-unit assignment and two-sided matching

• N, O are the sets of agents and goods,

- A (generalized) random assignment is a matrix $P = (P_{ia}) \in \mathbb{R}^{|N| \times |O|}$.
- *H* ⊂ 2^{N×O} is a collection of subsets of N × O, called a constraint structure.
- Integers $\underline{q}_{S} \leq \overline{q}_{S}$ for each $S \in \mathcal{H}$.
 - Each set $S \in \mathcal{H}$ is understood to be a "constraint set," that is, a set of elements on which a constraint is imposed. \underline{q}_S and \overline{q}_S are floor and ceiling (minimum and maximum) constraints, respectively. That is, we will consider random assignment Psatisfying

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$$P = \sum_{k=1}^{K} \lambda^k P^k$$
, such that

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 $e \underline{q}_{S} \leq \sum_{(i,a)\in S} P_{ia}^{k} \leq \overline{q}_{S}, \text{ for each } k \text{ and } S \in \mathcal{H}.$

 Decomposability means "Every P satisfying all the given constraints in H can be expressed as a convex combination of integral matrices satisfying the constraints." In other words, any random assignment satisfying constraints in H can be implemented as a lottery over deterministic assignments that satisfy constraints in H.

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Hierarchy

- What property of the constraint structure \mathcal{H} enables decomposability?
- $\mathcal{H} \subseteq 2^{N \times O}$ is a **hierarchy** if $S \cap S' = \emptyset$ or $S \subset S'$ or $S' \subset S$ for any $S, S' \in \mathcal{H}$.

$$\mathbf{P} = \begin{pmatrix} P_{1a} & P_{1b} & P_{1c} \\ P_{2a} & P_{2b} & P_{2c} \\ P_{3a} & P_{3b} & P_{3c} \end{pmatrix}$$

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H ⊆ 2^{*N*×*O*} is a **bihierarchy** if it can be partitioned into two hierarchies.

Theorem

If H forms a bihierarchy, then it is universally decomposable.

- Proof Sketch: Recognize that the set of feasible random assignments $\{P : \underline{q}_S \leq \sum_{(i,a) \in S} P_{ia} \leq \overline{q}_S$, for each $S \in \mathcal{H}\}$ forms a convex polyhedron. Any random assignment is thus a convex combination of extreme points. Suffices to show that the extreme points are integer-valued. This result follow from Hoffman and Kruskal (1956) and Edmonds (1970).
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- What can go wrong without bihierarchy?
 - 2 goods and 2 agents,

 $\mathcal{H} = \{\{(1,a),(1,b)\},\{(1,a),(2,a)\},\{(1,b),(2,a)\}\}, \text{ with }$

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Lemma

If $\mathcal H$ has an odd cycle of intersecting sets, then $\mathcal H$ is not universally decomposable.

Not generally but in a natural bilateral matching setting.

Theorem: Maximal domain

Suppose \mathcal{H} contains all "rows" ($\{i\} \times O, \forall i \in N$) and all "columns" ($N \times \{a\}, \forall a \in O$). If \mathcal{H} is not bihierarchical, then \mathcal{H} is not universally decomposable.

In many applications, row and column constraints are present. If this is the case, a bihierarchical structure is necessary for BvN decomposition.

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Example of a bihierarchy: Classical One to One Assignment

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The Birkhoff-von Neumann Theorem is a corollary of the Theorem.

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Suppose *a* and *b* are two programs within a school; each program has maximum capacity of 2, and the school has maximum capacity of 3.

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• Social planner needs to assign at most one object to each agent (e.g., school choice, housing allocation).

- Each agent has strict preferences over *O*.
- Some additional constraints are allowed; affirmative action constraints, flexible capacity, etc.
- Suppose constraint sets \mathcal{H} form a bihierchy.
 - ${\mathcal H}$ contains "rows."
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- **Random priority** (RP) mechanism: randomly order agents, and let each agent receive the favorite remaining good following the order, subject to the constraints described above. Ex post efficient but not ex ant efficient.

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Let $N = \{1, 2, 3, 4\}$, $O = \{a, b, c, ø\}$. Each good has quota of one, and only two out of three goods can actually be produced.

1 and 2 like a, b, ϕ (in this order), 3 and 4 like c, b, ϕ .

RP produces random assignment:

$$RP = \begin{pmatrix} 5/12 & 1/12 & 0 & 1/2 \\ 5/12 & 1/12 & 0 & 1/2 \\ 0 & 1/12 & 5/12 & 1/2 \\ 0 & 1/12 & 5/12 & 1/2 \end{pmatrix}$$

Everyone prefers

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$$RP = \begin{pmatrix} 5/12 & 1/12 & 0 & 1/2 \\ 5/12 & 1/12 & 0 & 1/2 \\ 0 & 1/12 & 5/12 & 1/2 \\ 0 & 1/12 & 5/12 & 1/2 \end{pmatrix}$$

Everyone prefers

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The Hylland Zeckhauser mechanism produces competitive equilibrium outcome in random assignment in one-to-one assignment. We generalize the mechanism to environments in which

- agents demand arbitrary multiple units with additively separable preferences over objects
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- For the case of simple additive-separable preferences, the HZ generalization is attractive: efficient, interim envy free, and strategyproof in the large economy.
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- Suppose agents may be assigned to multiple objects, and they have linear preferences in the values of assigned objects, {v_{ia}}.
- There are multiple ways to implement a random assignment, some less fair than others.
- Example: N = {1,2}; O = {a, b, c, d}, both have preferences a ≻ b ≻ c ≻ d; each agent demands 2 units.
 A random assignment

$$\mathbf{P} = \left(\begin{array}{rrrr} 0.5 & 0.5 & 0.5 & 0.5 \\ 0.5 & 0.5 & 0.5 & 0.5 \end{array}\right)$$

can be decomposed as

$$=\frac{1}{2}\left(\begin{array}{rrrr}1 & 1 & 0 & 0\\ 0 & 0 & 1 & 1\end{array}\right)+\frac{1}{2}\left(\begin{array}{rrrr}0 & 0 & 1 & 1\\ 1 & 1 & 0 & 0\end{array}\right)$$

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Theorem: One-sided utility guarantee

Given any random assignment $\mathbf{P} = (P_{ia})$, there exists a BvN decomposition of \mathbf{P} such that, for each $i \in N$, each ex post assignment in the decomposition gives i the expected utility within $\Delta_i := \max\{v_{ia} - v_{ib} | a, b \in O, P_{ia}, P_{ib} \notin \mathbb{Z}\}$ of that under \mathbf{P} .



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Theorem: Two-sided utility guarantee

Suppose both *N* and *O* are agents with strict preferences on the other side. Given any random assignment $\mathbf{P} = [P_{ia}]$, there exists a BvN decomposition of **P** such that, for each $i \in N$ and $a \in O$, each ex post assignment in the decomposition gives *i* the expected utility within $\Delta_i := \max\{v_{ia} - v_{ib}|a, b \in O, P_{ia}, P_{ib} \notin \mathbb{Z}\}$ of that under **P**, and $a \in O$ the expected utility within $\Delta_a := \max\{v_{ia} - v_{ja}|i, j \in N, P_{ia}, P_{ja} \notin \mathbb{Z}\}$ of that under **P**.

Suppose 8 (baseball) teams in two leagues, NL and AL, 4 teams in each league, must engage in interleague play — 6 games for each team against the teams in the other league. Wish to design equitable matchups.

List the teams in order of past performance (win/loss).

		AL						
		а	Ь	С	d			
NL	1	1.5	1.5	1.5	1.5			
	2	1.5	1.5	1.5	1.5			
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One Possible Outcome

		AL					
		а	b	С	d		
NL	1	2	1	1	2		
	2	1	2	2	1		
	3	1	2	2	1		
	4	2	1	1	2		

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